

Enhanced Optimization Scheme for Parallel PDE Solver of NSL

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Abstract

Authors have been developing a numerical simulation environment NSL [1], which automatically generates parallel PDE (partial differential equations) solver from high-level description of problem. Two of the notable features of NSL are boundary-fitted coordinate system and multi-block method. Physical domain is mapped onto a group of rectangular computational blocks, each of which is partitioned into one or more congruent sub-blocks. Each processor takes charge of a single sub-block. Static load balancing of such system can be modeled as a combinatorial optimization, which can be solved by branch-and-bound method [2][3]. However, in this model, the number of processors (n) is required to be greater than or equal to the number of blocks (m). This restriction can be a major obstacle to handle many blocks on a modest-scale parallel computer.

This paper presents an enhanced scheme that works regardless of the relationship between m and n , with additional performance improvement. Basic idea is that each processor handles a few sub-blocks instead of one. Assume that each processor is equivalent and in charge of the same number of sub-blocks. Let this number be k . The enhanced scheme is formulated as distributing kn virtual processors among m blocks and then allocating k sub-blocks for each physical processor. Applying the earlier algorithm [2][3] to kn virtual processors, the former part is easily solved. Let this result be $T_{m, kn}$. The latter allocation problem is beyond the scope of this short paper, so let us just take the worst case estimation here. The overall execution time T is estimated to be $kT_{m, kn}$.

Figure 1 shows the simulation results of T for various k , while both m and n are fixed to 16. No load balancing is achieved at $k = 1$, because n is equal to m . When block size (b) is small, T monotonically increases as k increases. In this case, calculation time is not enough to conceal communication latency and communication time increases in proportion to k . If b is big enough, T first decreases as k increases by the effect of load balancing when calculation time is superior to communication. At some point, communication is getting dominant and T turns to increase as k increases. Therefore, the execution time can be improved by choosing the optimal k . Figure 2 shows T for various m for $n = 16$ and $b = 200$. The new scheme applies to m that is bigger than n , while improving T with adequate k .

It is simple to implement this new scheme by iterating the earlier scheme for kn virtual processors until finding the optimal k . This new algorithm needs longer time than earlier because each search incurs $O((kn)^m)$ time in iteration. However, our simulation demonstrates that better solution can be derived in practical time.

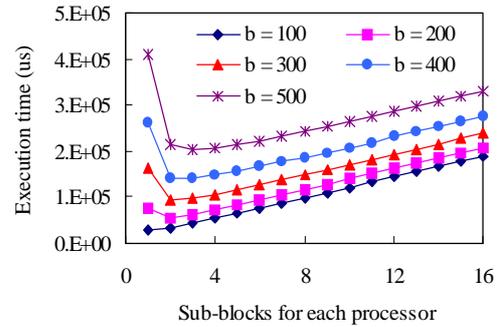


Figure 1. T vs. k

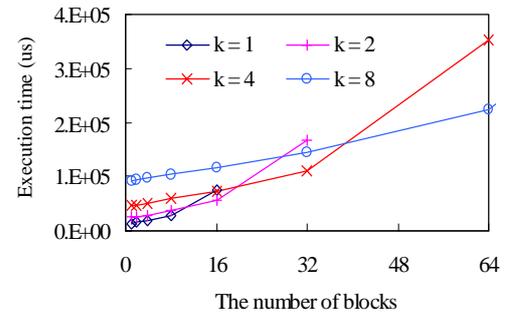


Figure 2. T vs. m

References

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